Kieran

* Sensor selection
  + FSRs
    - Looked at different options
  + Hall effect sensors
  + Pots
* Motors
  + Looked at lots of different options
    - DC
    - Servos
    - Strength stuff
* Code
  + Current progress
* Going forward
  + Changed to just up to elbows
  + Plan
    - Jack
      * Select elbow and forearm motor
      * Workshop forearm design and do design up to elbow
      * Build (and design) updated left arm and hand
      * Testing of arms
    - Kieran
      * Calibrate sensors
      * Thumb sensors
      * Add in PID positional control stuff
      * Create digital twin
      * Add in elbow and forearm motors
      * Program it to do something cool
      * Testing

Jack